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## PCA FUSION WITH IMAGE ENHANCEMENT FOR FACE RECOGNITION

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**Abstract:** - Image fusion is of great importance in biometric applications. This paper presents the PCA based image fusion technique to enhance illumination varying facial images used for face recognition system. Image fusion using Principal Component Analysis has been implemented and demonstrated in MATLAB software. Image enhancement algorithms such as Histogram equalization for contrast enhancement and Laplacian second derivative for image sharpening are applied on the facial image database before the calculation of the PCA component for fusion. For robustness of system various additive and multiplicative noises in the images such as Gaussian, Poisson, Salt and pepper, Speckle are introduced in the images. A comparative study is done with a PCA fusion method and PCA fusion method with image enhancement algorithms. The evaluation is done on the basis of quality parameters calculations, face recognition rate and concludes that the PCA fusion method with image enhancement algorithms shows better performance as compare to rest of the two algorithms.

**Keywords:** Principal Component Analysis, Image Fusion, Image Enhancement, Noises

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## INTRODUCTION

Principal Component Analysis Algorithm is a well known algorithm for dimension reduction and feature extraction. It is a way of identifying patterns in data, and expressing the data in such a way as to highlight their similarities and differences. Since patterns in data can be hard to find in data of high dimension, where the luxury of graphical representation is not available, PCA is a powerful tool for analyzing data. The other main advantage of PCA is that once you have found these patterns in the data, and you compress the data, i.e. by reducing the number of dimensions, without much loss of information. It is widely used in image classification and image compression. PCA involves the calculation of the eigen value decomposition of a data covariance matrix or singular value decomposition of a data matrix, usually after mean centering the data for each attribute. Principal component analysis (PCA) involves a mathematical procedure that transforms a number of possibly correlated variables into a smaller number of uncorrelated variables called principal components.

PCA is mathematically defined as an orthogonal linear transformation that transforms the data to a new coordinate system such that the greatest variance by any projection of the data comes to lie on the first coordinate (called the first principal component), the second greatest variance on the second coordinate, and so on. PCA is theoretically the optimum transform for given data in least square terms. For a given set of points in Euclidean space, the first principal component (the eigenvector with the largest eigenvalue) corresponds to a line that passes through the mean and minimizes sum squared error with those points. The second principal component corresponds to the same concept after all correlation with the first principal component has been subtracted out from the points. Each eigenvalue indicates the portion of the variance that is correlated with each eigenvector. Thus, the sum of all the eigenvalues is equal to the sum squared distance of the points with their mean divided by the number of dimensions. PCA essentially rotates the set of points around their mean in order to align with the first few principal components. This moves as much of the variance as possible (using a linear transformation) into the first few dimensions. The values in the remaining dimensions, therefore, tend to be highly correlated and may be dropped with minimal loss of information.

## FUSION ALGORITHM:

The details of PCA Fusion algorithm and PCA fusion Algorithm with image enhancement is described in this section. PCA based Image fusion algorithms are described in this paper. The fusion is done by weighted average of images to be fused. The weights for each source images

are calculated from the Eigen vector corresponding to the largest eigenvalues of the covariance matrices of each source.

Let the source images (image to be fused) be arranged in two-column vectors. The steps followed to project this data into a 2-D subspace are:

1. Organize the data in to column vectors. The resulting matrix Z is of dimension  $2 \times n$ .
2. Compute the empirical mean along each column. The empirical mean vector  $M_e$  has a dimension of  $1 \times 2$ .
3. Subtract the empirical mean vector  $M_e$  from each column of the data matrix Z. The resulting matrix X is of dimension  $2 \times n$ .
4. Find the covariance matrix C of X i.e.  $C = \text{XXT mean of expectation} = \text{Cov}(X)$ .
5. Compute the eigenvectors V and eigenvalues D of C and sort them by decreasing eigenvalue. Both V and D are of dimension  $2 \times 2$ .
6. Consider the first column of V which corresponds to larger eigenvalue to compute N1 and N2 as:

$$N1 = V(1) / \sum V \text{ and } N2 = V(2) / \sum V \quad (1)$$

The information flow diagram of PCA-based image fusion algorithm is shown in fig. below. The input images (images to be fused)  $I_f(x,y)$  and  $I_r(x,y)$  are arranged in two column vectors and their empirical means are subtracted. The resulting vector has a dimension of  $n \times 2$ , where n is length of the each image vector. Compute the eigenvector and eigenvalues for this resulting vector are computed and the eigenvectors corresponding to the larger eigenvalue obtained. The normalized components N1 and N2 (i.e.,  $N1 + N2 = 1$ ) are computed from the obtained eigenvector. The fused image is:

$$I_{\text{fused}}(x,y) = N1 I_f(x,y) + N2 I_r(x,y) \quad (2)$$

#### IMAGE ENHANCEMENT TECHNIQUES:

- Histogram Equalization for contrast enhancement
- Laplacian second derivative for image sharpening

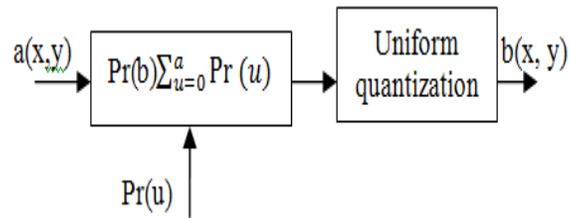


Fig 1: - Histogram Equalization Process

**EQUALIZING THE HISTOGRAM:**

Input histogram P1 (a) shown as probability density.

First output histogram P2(b)

Cumulative input histogram F1 (a0, increasing from 0 to 1,

Where  $F(a) = \sum_{u=0}^a Pr(u)$  has been selected.

Linear cumulative output histogram F2 (b).

**LAPLACIAN SECOND ORDER DERIVATIVE FOR IMAGE SHARPENING:**

We are interested in isotropic filters, whose response is independent of the direction of the discontinuities in the image to which the filter is applied. Isotropic filters are rotation invariant, in the sense that rotating the image and then applying the filter gives the same results as applying the filter to the image first and then rotating the result.

It can be shown that the simplest isotropic derivative operator is the Laplacian; which, for a function (image)  $f(x, y)$  of two variables, is defined as

$$\Delta^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} \quad (3)$$

Because derivatives of any order are linear operations, the Laplacian is a linear operator.

Laplacian is a derivative operator; its use highlights intensity discontinuities in an image and deemphasizes regions with slowly varying intensity levels. This will tend to produce images that have grayish edge lines and other discontinuities, all superimposed on a dark featureless background. Background features can be 'recovered' while still preserving the sharpening effect of the Laplacian image to the original.

$$G(x,y) = F(x,y) + C[\Delta^2F(x,y)] \quad (4)$$

C=1 if centre value of the filter mask is positive.

Else C= -1, F(x,y): image to process.

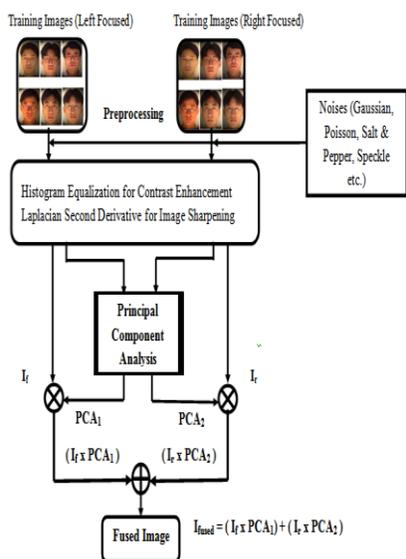
$$\text{Mask} = \begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

Using MATLAB functions:

- Result\_img= conv2(original\_img,mask);
- R= Result\_img(2: (ht-1), 2 :(wt-1));
- Final= Original\_img + R

Adding original image to the Laplacian restored the overall intensity variations in the image, with the Laplacian increasing the contrast at the locations of intensity discontinuities. Small details are enhanced and background tonality preserved.

**PROPOSED SYSTEM BLOCK DIAGRAM:**



**Fig 2: System Block Diagram**

**RESULTS:**

Noises	Recognition Rates (%)	
	PCA Fusion	PCA Fusion with Image Enhancement Method
Gaussian	74	78
Poisson	76	81
Salt & Pepper	66	75
Speckle	79	85

**Table 1 (Comparative Recognition Rates)**

Parameters	PCA Fusion	PCA Fusion with Image Enhancement Method
PSNR (dB)	18.55	19.31
CORR	0.83	0.84
MI	2.25	2.26
SSIM	0.90	0.91
RMSE	9.33	9.34
UQI	0.89	0.90
SF	12.82	13.45

**Table 2: Quality Parameters Calculations**

**NOMENCLATURE**

<b>CORR</b>	<b>Correlation</b>
<b>MI</b>	<b>Mutual Information</b>
<b>SSIM</b>	<b>Measure of Structural Similarity</b>
<b>RMSE</b>	<b>Root Mean Square Error</b>
<b>UQI</b>	<b>Universal Quality Index</b>
<b>SF</b>	<b>Spatial Frequency</b>
<b>PSNR</b>	<b>Peak Signal to Noise Ratio</b>

**CONCLUSION**

Comparative study of PCA Fusion technique and PCA Fusion with Image enhancement technique is implemented here in this paper. In PCA fusion with image enhancement technique the Histogram equalization for contrast enhancement and Laplacian second derivative for

image sharpening is used for different image fusion performance metrics with reference image have been evaluated. The PCA fusion algorithm shows degraded performance but Image fusion with Image enhancement technique shows better performance. Because the change of illumination effect is reduced by Histogram Equalization method, i.e. This Technique uniformly distributes the illumination effect and preserves the entropy of image. And sharpening algorithm is used for sharpening the edges of face images, so that it will increase the accuracy of recognition. Here the Edge and Contrast are the salient features of the facial images; these salient features i.e. Edge is improved by Laplacian Gaussian method and Contrast by Histogram Equalization method, Which results in improvement in recognition rate.

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